

In vitro Assessment of Aortic Regurgitation Using Four-Dimensional Flow Magnetic Resonance Imaging

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Abstract

Aortic regurgitation (AR) refers to backward blood flow from the aorta into the left ventricle (LV) during ventricular diastole. The regurgitant jet arising from the complex shape is characterized by the three-dimensional flow and high-velocity gradient, sometimes limiting an accurate measurement of the regurgitant volume using 2D echocardiography. Recently developed four-dimensional flow magnetic resonance imaging (4D flow MRI) enables three-dimensional volumetric flow measurements, which can be used to accurately quantify the amount of the regurgitation. This study focuses on (i) magnetic resonance compatible AR model fabrication (dilatation, perforation, and prolapse) and (ii) systematic analysis of the performance of 4D flow MRI in AR quantification. The results indicated that the formation of the forward and backward jets over time was highly dependent on the types of AR origin. The amount of regurgitation volume bias for the model types were -7.04%, -33.21%, 6.75%, and 37.04% compared to the ground truth (48 mL) volume measured from the pump stroke volume. The largest error of the regurgitation fraction was around 12%. These results indicate that careful selection of imaging parameters is required when absolute regurgitation volume is important. The suggested *in vitro* flow phantom can easily be modified to simulate other valvular diseases such as aortic stenosis or bicuspid aortic valve (BAV) and can be used as a standard platform to test different MRI sequences in the future.

Introduction

Aortic regurgitation (AR) refers to the backward flow from the aorta into the left ventricle during the diastolic phase of the ventricle. AR is typically classified into aortic dilatation, cups prolapse, cups perforation, cups retraction, and others¹. Chronic AR may cause the volume overload of the LV mainly

due to hypertrophy and dilatation, and eventually causes its decompensation². Acute AR is mainly caused by infectious endocarditis, aortic dissection, and traumatic rupture, which leads to hemodynamic emergencies².

Current clinical standards for AR diagnosis are mainly based on transthoracic echocardiography (TTE) or transesophageal echocardiography (TEE)³. Despite the advantages of real-time imaging and short exam time, the accuracy of echocardiography is highly operator-dependent. Especially for the regurgitant volume measurement, direct measurement of the regurgitant volume is limited as the regurgitant jet shifts out of the two-dimensional (2D) measurement plane due to the motion of the aortic valve. Indirect estimation using proximal iso-velocity surface area (PISA) methods are often used, but assumptions such as circular orifice area often limit the accurate measurement⁴.

Recent medical guidelines⁵ also recommend cardiac MR (CMR), especially for moderate or severe AR patients to compensate for the limitation of echocardiography by measuring the mass and global function of the LV. Structural parameters such as aortic leaflets and LV size, and flow parameters such as jet width, vena contracta width, and regurgitant volume can also be comprehensively considered in AR diagnosis⁶. However, aortic regurgitation volume estimated with the LV global function may fail especially for patients with other heart valvular diseases or shunt.

Alternatively, 4D flow MRI has been considered as a promising technique that can directly measure the regurgitant volume with time-resolved velocity information within the volume of interest⁷. The motion of the valve according to the time can be easily tracked and compensated when measuring the regurgitant flow volume^{8,9}. Also, an arbitrary plane perpendicular to the regurgitant jet can be retrospectively positioned, which increases the accuracy of the measurement¹⁰. However, as the 4D flow MRI inherently obtains the spatiotemporally averaged information,

the accuracy of this technique still warrants validation by using well-controlled *in vitro* flow experiments.

This study aims to (i) develop MRI compatible *in vitro* experimental platform that can reproduce the different clinical scenarios of AR (dilatation, perforation, and prolapse) and (ii) enrich our understanding of 4D flow MRI performance in quantifying different AR at these AR models. In addition, 3D hemodynamic visualization and quantification based on 4D flow MRI were conducted according to the various clinical scenarios. This protocol is not limited to AR and can be extended to other types of valvular disease studies that require a series of *in vitro* experiments and hemodynamic quantification.

Protocol

NOTE: The protocol is largely composed of three stages: (1) model fabrication, (2) MRI scan and parameter selection, and (3) data analysis. **Figure 1** is a flow diagram showing the overall process of the protocol.

1. Model fabrication

1. Aortic root model

1. As shown in **Figure 2**, determine the parameter values of the aortic root, such as valve base diameter and sinus radius. For this experiment, the values were $D_A = 32.24$ mm, $D_O = 26$ mm, $L_B = 8.84$ mm, $L_A = 26$ mm, $r_{min} = 16.64$ mm, $r_{max} = 21.32$ mm.
2. Run the 3D modeling software by clicking **Sketch > Tools Sketch Tools > Sketch Picture**.

NOTE: Solidwork is used for 3D modeling in the experiment.

3. To make a sinus model, sketch circles corresponding to r_{\max} and r_{\min} using the circle tool. Draw a curved line of the sinus using the free curve function¹¹, click **Loft Tool** and select the sketch area for loft.
 4. Sketch additional circles on the top and bottom of the current model, click **Extrude Tool**, and select the circles. Set the options as 20 mm downward and 30 mm upward. Make a hexahedron model of size 100 mm x 100 mm x 76 mm in the same way.
 5. Click **Combine Tool from Insert > Features > Combine**. Select **Subtract** in the property manager. Select the hexahedron model and the sinus model. Fabricate the final design as an acrylic model with a 5-axis CNC machine as per manufacturer's instruction.
2. Valve frame
1. Run 3D modeling software and open a new sketch. Draw a square of size 100 mm x 100 mm and a circle of 25 mm in the center for the valve base, manually. Click the **Extrude Tool** and adjust the height of the valve base to 5 mm.
 2. Extrude the circle with a height of 23.5 mm and a thickness of 3 mm thick. Divide the model into 12 uniform pieces using **Line Tool** so that each piece has 30°. Select three pieces with 120° intervals and extrude with a height of 16.5 mm to make three pillars.
 3. Click **Fillet Tool** and select the pillars. Adjust the fillet radius at the top and bottom as 4 mm and 10 mm, respectively. Save it in an STL file format.
 4. 3D-print the valve frame. Set the infill density to 100% and use acrylonitrile butadiene styrene as fill material. See **Figure 3** for the shape and dimensions of the aortic valve frame.
3. Aortic regurgitation model using expanded polytetrafluoroethylene (ePTFE)
1. Run the 3D modeling software and open a new sketch. Draw a horizontal line of 23.24 mm and a vertical line of 15 mm with reference to **Figure 4A**.
NOTE: The geometric parameters of the valve's base, height, and leaflet free-edge length were chosen according to a previous study¹².
 2. Click **3 Point Arc Tool** from the arc command manager and set two points on each end of the horizontal line and the last point on the end of the vertical line. Extrude the sketch with a thickness of 5 mm. Export the model with STL file format and 3D print it.
 3. Overlap the ePTFE membrane in two layers and draw three leaflet borders at intervals of 2 mm using the printed leaflet. Suture along the drawn lines and side borders at 1 mm intervals with a polyamide suture with a diameter of 0.1 mm. Suture the ePTFE valve from top to bottom on the frame at 1 mm intervals.
 4. Cut the outer side of the membrane and suture it with each other. Perform the following three modifications to obtain three different models.
 1. Dilatation model: Reduce the ratio of the designed leaflet parameters to 90%.

2. Perforation model: Make a circular hole with a diameter of 2 mm using scissors in the center of one leaflet.
3. Prolapse: Fix the two commissures of the valve at a hole with a low post height.

NOTE: **Figure 4** shows the materials and fabrication method of ePTFE valve. **Figure 5** shows the characteristics of each AR-type.

2. MRI scan and parameter selection

1. Prepare the experimental system consisting of an AR model, aortic sinus model, a heart simulation pump, and MRI.
2. Set the experiment models in the MRI room and connect the pump, reservoir, and models using a 25 mm (inner diameter) silicone tube. Use a 10 cm long cable tie to fasten the connection parts to prevent possible leakage.
3. Use a motor-controlled piston pump to simulate the aortic blood flow waveforms to generate a physiological flow waveform through the flow circuit system. Use water as the working fluid and attach one-way valves to the inlet and outlet to prevent backflow. Details of the flow pump can be found in the previous study²³.
4. Locate the model within the field of view (FOV) of the MRI. Perform a scout scan to observe phantom images in the coronal, axial, and sagittal views in MRI operating console monitor. This image is used as a guide to position the following image sequences.
5. Locate the 2D image plane in the center of the aorta model. Run a variable velocity-encoding parameter (VENC) 2D phase-contrast imaging to select the most appropriate VENC value for 4D flow MRI.
6. Set VENC to a 10% higher value in 4D flow MRI to minimize possible velocity aliasing⁷. Enter the desired spatial resolution and the temporal resolution on the MRI console. The spatial and temporal resolution for the aortic flow is recommended to be 2-3 mm and 20-40 ms, respectively⁷. **Table 2** shows the MRI scan parameters.
7. Acquire data for both with and without flow using the 3 types of AR valves and the without valve.

3. Data analysis

1. Data sorting and correction
 1. Copy raw data files from the scanner to proceed with the data analysis. Sort the dicom files according to the header named series description using the Dicom sort software. Click **Sort Images** in Dicom sort software to sort three-directional phase images and magnitude images in separate folders.
 2. Load magnitude image into the ITK-snap software. Click **Brush** in the ITK-snap and manually paint the internal fluid region of the phantom using the brush tool. Save segmented image.
 3. (Optional) Load both phase image data obtained with the flow on and off using MATLAB. Subtract the data with the flow by the data without flow to remove background errors. Repeat this for every direction and cardiac cycle.
 4. Calculate the velocity of 5D matrix phase data (row x column x slice x direction x time) using a vendor-specific pixel-to-velocity equation. In general, the maximum intensity of the pixel corresponds to the selected VENC value.
2. Visualization

1. Load the 5D matrix velocity from step 3.1.4 into flow visualization analysis software.

NOTE: Input velocity matrix may vary according to the analysis software. Enight users should follow Enight gold case format guide¹³.

2. Click the **Isosurface Part**, change the data type from isosurface to isovolume for 3D analysis by clicking the **Isovolume** button. Drag the speed data in the variables command manager, add it to the isovolume to check the velocity distribution of the model.
3. Click **Particle Trace Emitters Tool** in the main menu. Check **Advanced Option** for a more accurate analysis. Select the desired visualization such as **Streamlines** or **Pathlines** in creation.
4. For this experiment, set the following value: Emit From Option = Part, Part ID = 2, No. of Emitters = 10000, Direction = +/- . Create and check the results over time.
5. Right-click the **Particle Trace** model and click the **Color by**. Select the velocity component to color the streamline with the velocity.

3. Quantification

1. Load the velocity data (step 3.1.4) and segmented image (step 3.1.2) onto MATLAB. Set the velocity outside of the segmentation region to zero. This can be easily performed by elementwise multiplying the segmented matrix data and the velocity matrix data.
2. Check if the velocity data has phase-wrapping using the **imshow** function of MATLAB. Inversion of the velocity direction indicates phase-wrapping.

3. Slice the desired plane of the matrix data. Sum all velocity data within the plane and multiply spatial resolution to calculate the flow rate through the plane. Sum all flow rates throughout the cardiac cycle and multiply the temporal resolution to calculate the stroke volume.

Representative Results

Three representative classes of aortic regurgitation models were fabricated, and one case without a valve was fabricated for comparison (**Figure 3**). The dilation model clearly showed incomplete closure of the valve leaflet due to the smaller-sized leaflets. A hole was punctured on one of the leaflets using scissors to mimic the perforation model. One leaflet of the prolapse model looked smaller than the other two leaflets because the two commissures were sutured at a position lower than the original height. There were no significant differences from the top view.

With the 3D velocity information acquired over time using 4D flow MRI, streamlines of normal and regurgitation jets were visualized during systole and diastole (**Figure 6**). The forward jet was straight in all models except for the perforation model. In the perforation model, a wall-biased jet occurred during the systole phase. The regurgitating jet showed a different velocity and shape according to the AR classification. In the case of without a valve, an overall forward and backward flow occurred. The regurgitant jet of the dilation model came out from the center and tended to change directions over time. The perforation and prolapse model regurgitant jet leaned toward the wall. The peak velocity of the forward and regurgitant jet was 0.28 m/s, -0.29 m/s in the model without valve, 2.03 m/s, -3.53 m/s in the dilatation model, 2.52 m/s,

-3.13 m/s in the perforation model, and 2.76 m/s, -2.88 m/s in the prolapse model.

Figure 7 shows the flow rate for each valve and the forward and regurgitant volumes in a 3D plane away from the valve base. The flow rates showed different waveforms and quantities for each model. The amount of regurgitation volume was 51.38 mL, 63.94 mL, 44.76 mL, and 30.22 mL for without valve, dilatation, perforation, and prolapse models, respectively. The bias for without valve, dilatation,

perforation, and prolapse model were -7.04%, -33.21%, 6.75%, and 37.04%, respectively, compared to the ground truth (48 mL) measured from the pump stroke volume. The positive percentage values indicate underestimation while the negative percentage values represent over estimation. The regurgitation fraction error was -7.78%, -6.00%, 0.33% and -11.18% for without valve, dilatation, perforation and prolapse model, respectively.

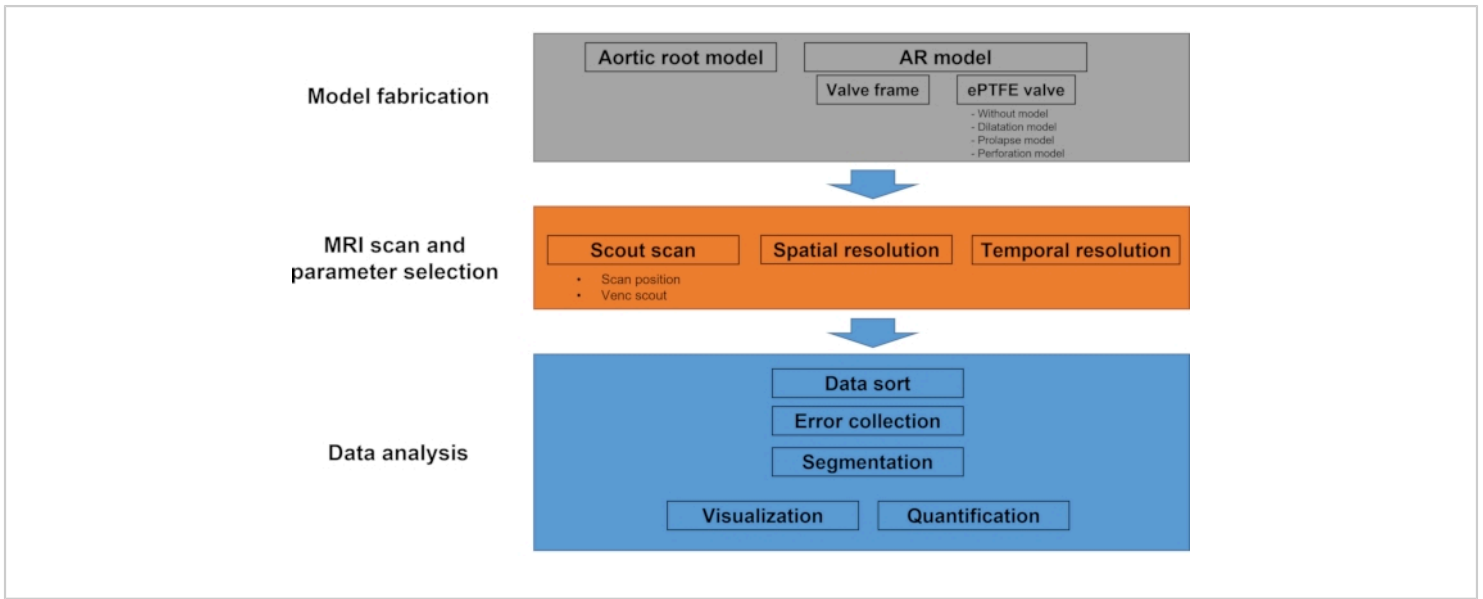


Figure 1: Workflow diagram of the protocol. This experimental protocol mainly consists of model fabrication, MRI scan, and data analysis. In the model fabrication step, the outer aortic root model and four different types of AR model (without valve, dilatation, prolapse, and perforation) are fabricated. During the MRI scan, scout imaging followed by multi-VENC scan and 4D flow MRI is performed. The data analysis part includes data sorting, image segmentation, velocity calculation, visualization, and quantification. [Please click here to view a larger version of this figure.](#)

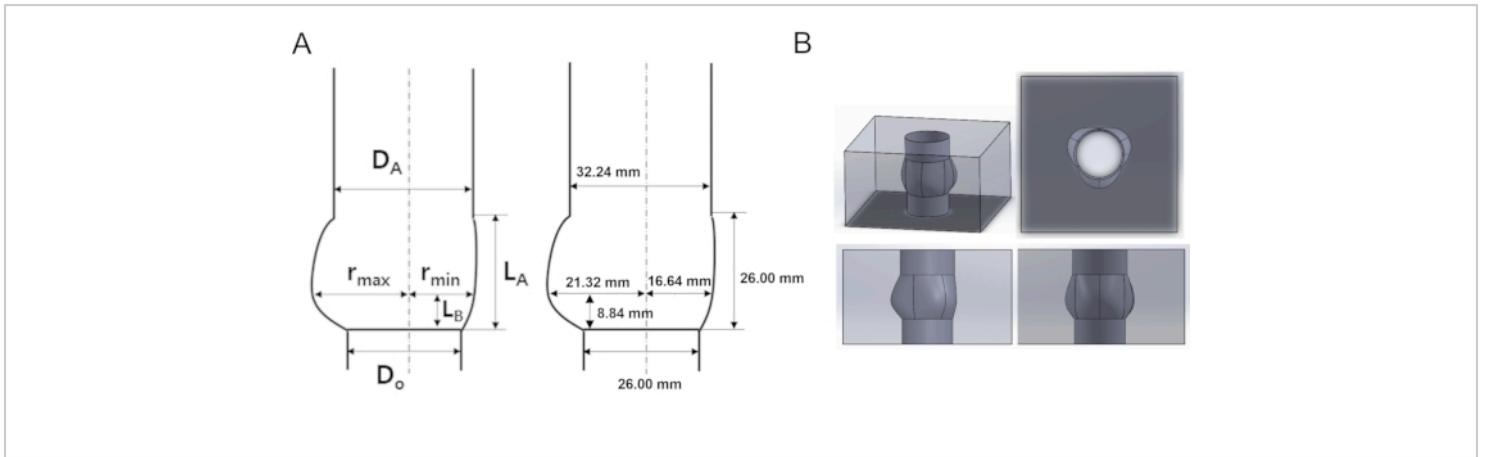


Figure 2: Schematic and designed acrylic model of the aortic root (A) Geometrical characterization and parameters of the aortic root geometry. **(B)** Aortic root 3D model in multi-dimensional view. D_A : diameter of sinotubular junction (STJ), D_O : diameter of annulus, r_{max} : maximum sinus diameter, r_{min} : minimum sinus diameter, L_A : height of sinus, L_B : height of STJ.

[Please click here to view a larger version of this figure.](#)

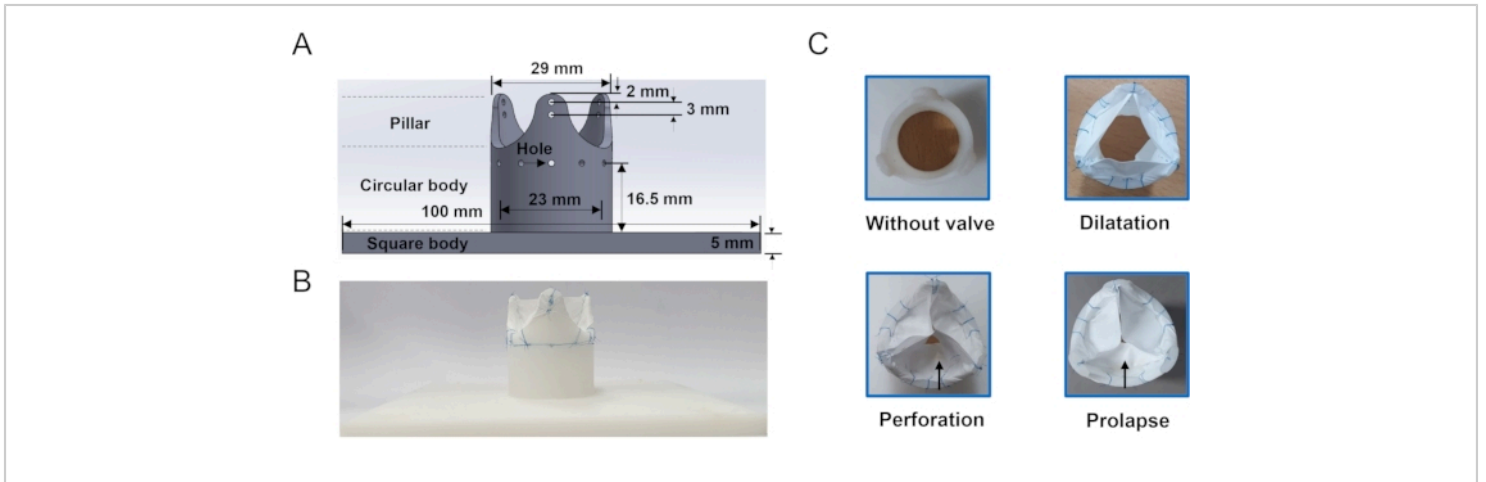


Figure 3: Aortic regurgitation frame and model (A) Geometrical information of the aortic valve frame which is used to hold the leaflet. Holes around the body of the frame is where the suture line passes. **(B)** Example of ePTFE membrane sutured valve. **(C)** En-face view of the *in vitro* models: without valve, dilation, perforation and prolapse fabricated in this study. The arrow indicates the damaged cusp. [Please click here to view a larger version of this figure.](#)

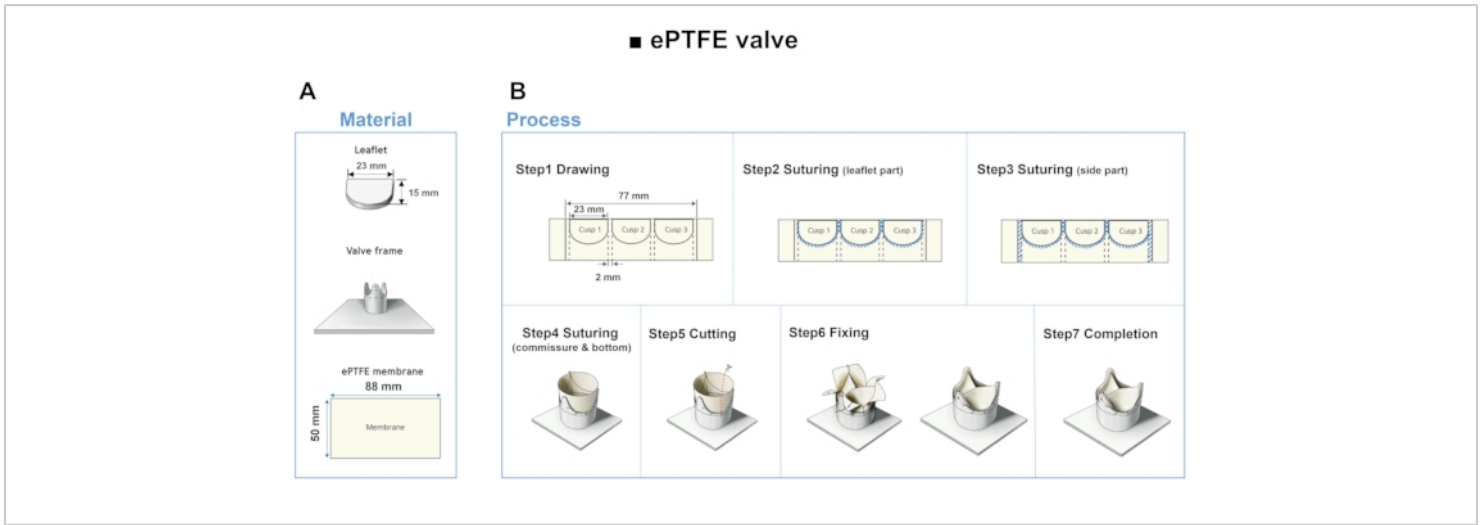


Figure 4: Material and fabrication step of ePTFE leaflet. (A) Using 3D printed leaflets as a guide, leaflets are made using ePTFE membrane. (B) Drawing, suturing, cutting and fixing steps of the ePTFE valve. [Please click here to view a larger version of this figure.](#)

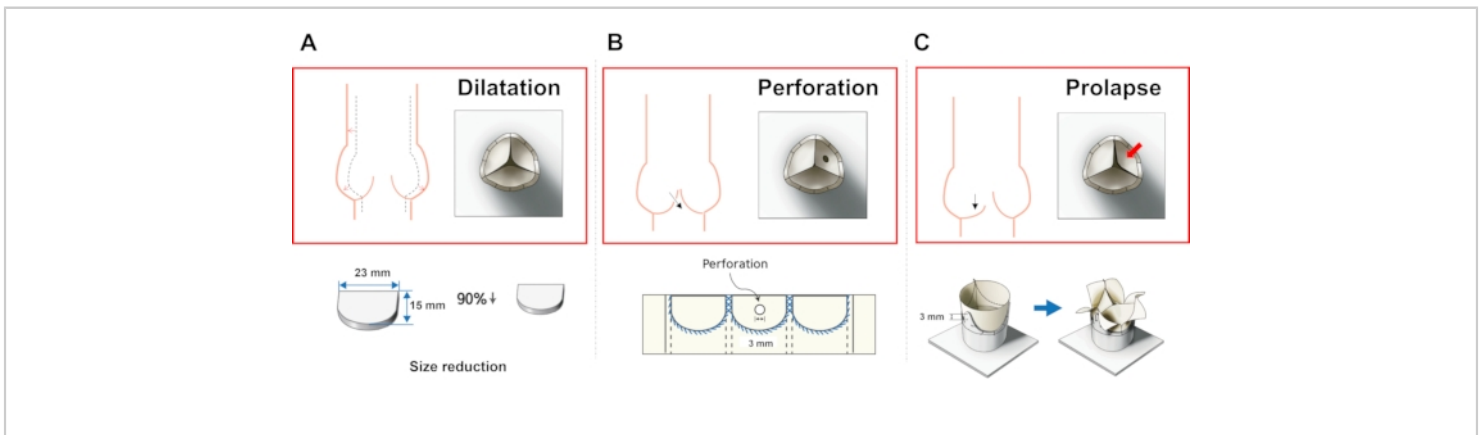


Figure 5: Fabrication methods of different AR models. (A) Dilatation model, (B) perforation model, and (C) prolapse model. [Please click here to view a larger version of this figure.](#)

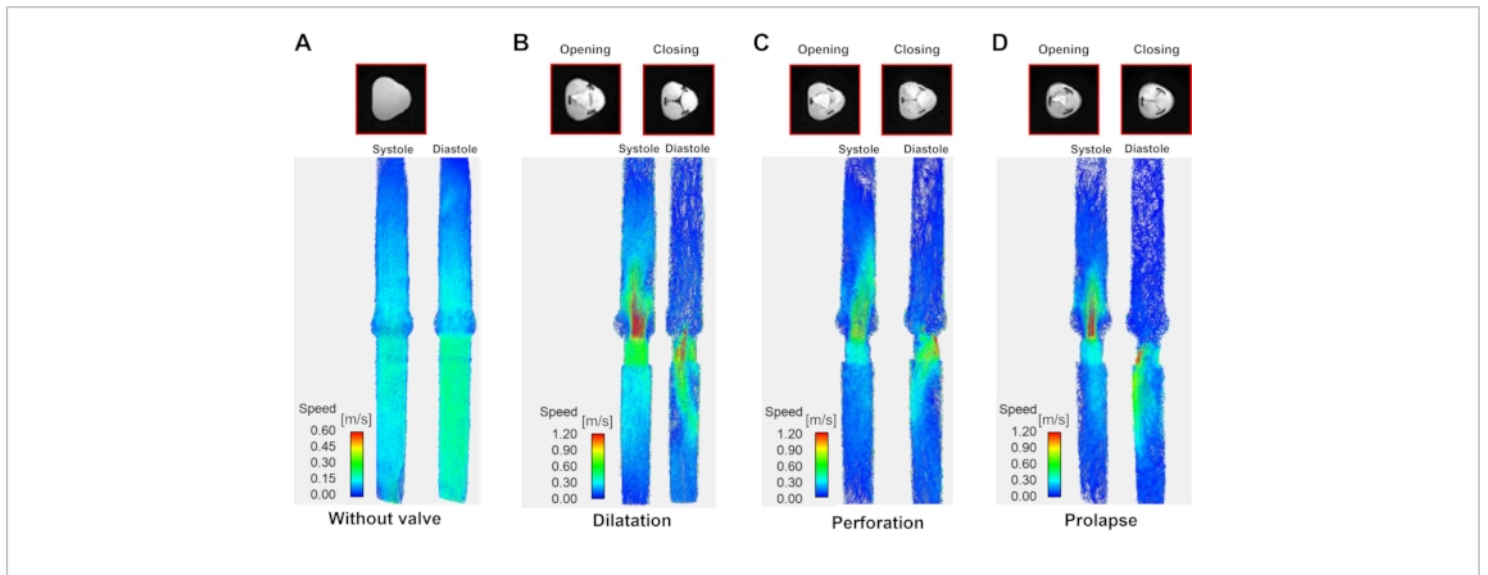


Figure 6: Streamline visualization according to aortic regurgitation type. A streamline visualization at systole (left of each panel) and diastole (right of each panel) according to aortic regurgitation type. **(A)** Model without valve (the diastole/systole image are the same due to lack of a valve), **(B)** dilatation, **(C)** perforation, and **(D)** prolapse. Systole and diastole data were taken where the inlet velocity is the highest and the lowest during the cardiac cycle. [Please click here to view a larger version of this figure.](#)

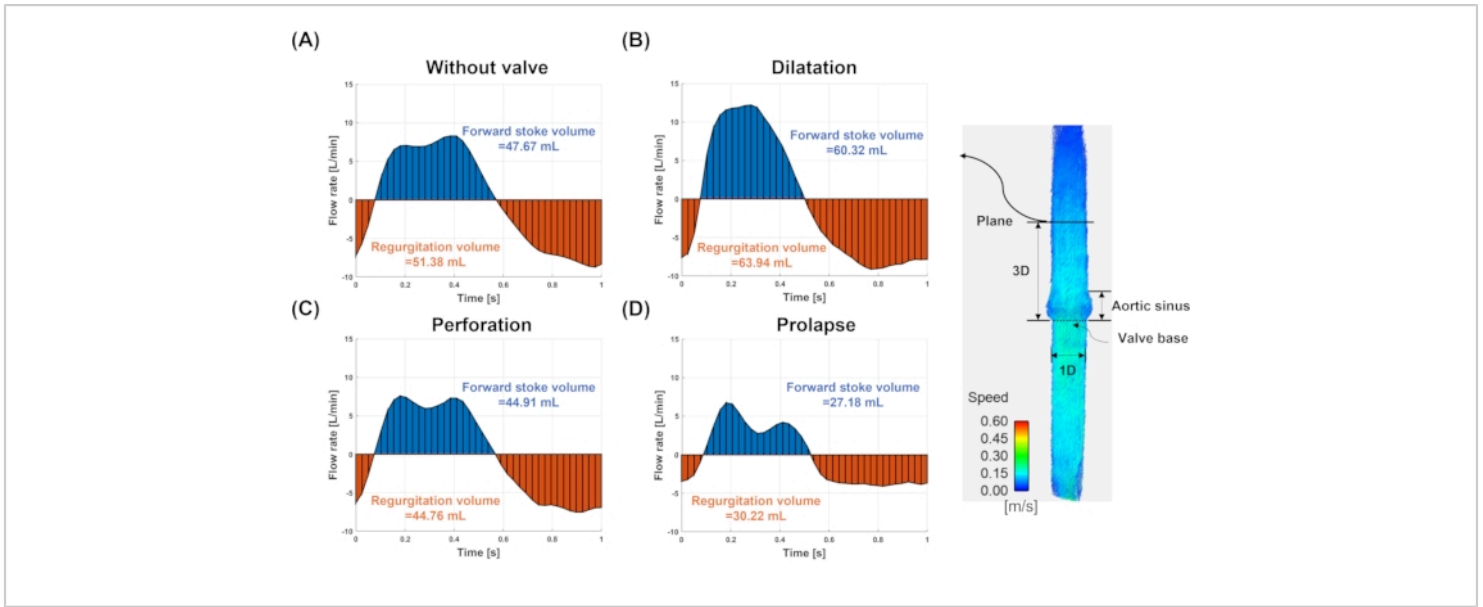


Figure 7: Flow rate and stroke volume. The flow rate and stroke volume for (A) model without valve, (B) dilatation, (C) perforation, and (D) prolapse. The flow rate and stroke volume are measured at the plane (solid line) three-diameter downstream to the valve annulus. The blue and red colors indicate the forward and regurgitating flows, respectively. [Please click here to view a larger version of this figure.](#)

Ratio ($D_0 = 26$ mm)	D_A/D_0	L_A/D_0	L_B/D_0	r_{max}/D_0	r_{min}/D_0
	1.24	1	0.34	0.82	0.64

Table 1. Geometrical parameters of the aortic root geometry shown in Figure 1.

Temporal resolution	0.025 ms/40 phases
Spatial resolution	2mm x 2mm/0.5 pixel per 1 mm
Matrix	96 x 160 x 26 pixel
Slice thickness	2 mm
Echo time	2.54 ms
Encoding velocity	25-330 cm/s

Table 2. 4D Flow MRI sequence parameters *in vitro*.

Discussion

Four-dimensional flow MRI has recently been verified by various *ex vivo* and *in vivo* studies as an application for clinical routine use¹⁴. As the 4D flow MRI obtains 3D velocity information over the entire cardiac cycle, one strong application is a direct quantification of the valvular regurgitant volume, which conventional 2D Doppler echocardiography is not capable of quantifying¹⁵. *In vitro* experiments using 4D Flow MRI can provide the 3D flow velocity and related hemodynamic parameters which can be used for investigating the relationship between cardiovascular disease and hemodynamics. However, despite its promising capability, no systematic studies on this application have been reported yet. This is possibly due to the lack of well-controlled *in vitro* experiments that mimic the regurgitation of the tri-leaflet valves.

Recent developments in *in vitro* studies have provided more accurate and realistic experimental methods to access the pre- and post-valvular hemodynamics^{16,17}. Coupled with an optical image-based particle image velocimetry (PIV), accurate measurement and quantification of the flow around the valve was possible in previous *in vitro* studies¹⁸. However, accurate 3D flow fields, especially for the post-valvular flow, were limited owing to the opaque model and refraction. On the other hand, 3D velocity measurements using MRI were also limited, as metal components cannot be used^{19,20}.

Hence in this study, a protocol to build a flow experimental platform that is MR compatible and highly modifiable to reproduce various clinical scenarios of valvular diseases is introduced. The ePTFE membrane is used to mimic the tricuspid valve without metal components as it has been widely used as a valve and vascular graft material due to

its high tensile strength and chemical resistance^{17,21,22}. Based on ePTFE films, three different origins of the AR have been reproduced (dilatation, perforation, and prolapse) as well as a model without a valve for comparison. The next important step in this flow experimental protocol is MR imaging and quantification. A motor-controlled piston pump that can simulate the aortic blood flow waveforms is used to generate a physiological flow waveform through the flow circuit system. Details of the flow pump can be found in the previous study²³. As this study also aims to validate the accuracy of the 4D flow MRI in flow quantification, all the imaging parameters are selected based on the previous study which summarizes the parameters that can be used in the clinical routine²⁴. As the MRI system includes inherent errors due to imperfections such as eddy currents and nonlinearity of the magnetic field²⁵, the background correction strategy is applied prior to the actual data quantification as described in step 3.1.3.

The hand-made aortic regurgitation model suggested in this study showed similar hemodynamic characteristics of regurgitant jet according to model classification as previous studies reported^{26,27}. The closed shape was symmetrical, and a straight jet occurred at the center of the valve in the dilatation model. A posteriorly directed eccentric jet appears owing to cusp damage in the perforation model. Partial prolapse of the valve shows a jet whose direction was bent from the culprit cup owing to limited mobility. The aortic regurgitation volume directly measured using the 4D flow MRI was overestimated in the without valve and dilatation model, while it was largely underestimated in the prolapse model when compared with the ground truth. However, when the regurgitant fraction was calculated, the largest bias was only 11% in the prolapse model. This strongly indicates that not only the regurgitant flow but also the normal aortic

jet was affected by the MR scan. At the current stage, individual scan parameters were not optimized for each AR model. A future systemic parameter study may improve the accuracy of regurgitant volume measurement. Alternatively, the use of regurgitant fraction is more robust as it cancels out the inherent errors in 4D flow MRI but also is clinically more relevant than simply measuring the absolute regurgitant volume.

In conclusion, this study suggests an MR compatible *in vitro* flow experimental model that is highly modifiable to simulate various types of AR. Also, the accuracy of AR volume measurement using 4D flow MRI was compared. The limitation of this study is that the motion of the aortic valve was not simulated, which can affect the actual development of the regurgitant jet. In addition, the partial volume effect and temporal averaging nature of the 4D-flow MRI may limit the accuracy of the flow measurement, especially considering the high dynamic range of velocity within the jet and surroundings. Therefore, further systematic parameter study is required.

Disclosures

The authors have nothing to disclose.

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